

## Math 307: homework problems 3

1. Are the vectors  $\begin{bmatrix} 1 \\ 2 \\ 1 \\ 2 \\ 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 \\ -1 \\ 3 \\ -2 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} 0 \\ 0 \\ -2 \\ 0 \\ 1 \end{bmatrix}$ ,  $\begin{bmatrix} 0 \\ 4 \\ -9 \\ 7 \\ 3 \end{bmatrix}$  linearly independent?

2. If  $\mathbf{rref}(A) = \begin{bmatrix} 1 & a & 0 & b & d & 0 \\ 0 & 0 & 1 & c & e & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$  find a basis for  $N(A)$  and  $R(A^T)$ .

3. Explain why the first three rows of the matrix in Q2 are linearly independent.

4. Find the rank  $\mathbf{r}(A)$  and bases for  $N(A)$ ,  $R(A)$ ,  $N(A^T)$ ,  $R(A^T)$  when  $A = \begin{bmatrix} 1 & 2 & 0 & 2 & 1 & 0 \\ 1 & 2 & 1 & 5 & 3 & 0 \\ 1 & 2 & 1 & 5 & 3 & 1 \\ 1 & 2 & 1 & 5 & 3 & 1 \end{bmatrix}$ .

5. Show that if  $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$  are linearly independent and  $E$  is invertible then  $E\mathbf{u}_1, E\mathbf{u}_2, \dots, E\mathbf{u}_k$  are also linearly independent. Is this still true if  $E$  is not invertible?

6. We saw in class that the set of polynomials of degree at most  $n$  form a subspace (of functions). If we take  $n = 2$ , then a general quadratic polynomial can be written as  $p(x) = c_0 + c_1x + c_2x^2$ . We can

represent this polynomial by the vector  $\mathbf{p} = \begin{bmatrix} c_0 \\ c_1 \\ c_2 \end{bmatrix}$ . The derivative of  $p(x)$  is  $q(x) = c_1 + 2c_2x$ , which

may be represented by the vector  $\mathbf{q} = \begin{bmatrix} c_1 \\ 2c_2 \\ 0 \end{bmatrix}$ .

Show that the matrix

$$D_2 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

satisfies  $D_2\mathbf{p} = \mathbf{q}$  (and so  $D_2$  represents the derivative).

If we change the value of  $n$ , then the dimension increases. Find the matrix  $D_n$  representing the derivative for degree  $n$  polynomials.

What is the nullspace of  $D_n$ ?

What is the range of  $D_n$ ?

Show that there is no solution to  $(D_n - I)\mathbf{p} = \mathbf{0}$  except  $\mathbf{p} = \mathbf{0}$ . (It is easiest to do this problem by reverting to a differential equation and using properties of the derivative and polynomials of degree  $n$ .)

7. (Bonus) We showed above that the derivative acting on polynomials of degree  $n$  behaves much like a matrix acting on vectors. Here we extend some of those properties to the set of smooth functions (functions for which all derivatives exist) rather than just polynomials. We can now no longer represent the function directly as a vector or derivatives as matrices.

We represent the derivative by  $D$ , so that  $Df(x)$  is the derivative of  $f(x)$  [you've previously seen  $df/dx$  or  $f'(x)$  as other ways to write this].

Find the nullspace of  $D$ .

Find the nullspace of  $D^n$ .

Show that  $e^{rx}$  is in the nullspace of  $D - rI$ , where  $I$  is the identity:  $If(x) = f(x)$ .

Find the nullspace of  $(D - rI)^2$ . (*Hint: use integrating factors.*)

Find the nullspace of  $(D - rI)^n$ .

8. (Optional) The differential equation  $f''(x) - (r_1 + r_2)f'(x) + r_1r_2f(x) = 0$  may be written as

$$[D^2 - (r_1 + r_2)D + r_1r_2I]f(x) = 0$$

We may also write this as  $P(D)f(x) = 0$  where  $P(D) = D^2 - (r_1 + r_2)D + r_1r_2I$ . It is possible to factor  $P(D)$  into either  $(D - r_1)(D - r_2)$  or  $(D - r_2)(D - r_1)$ .

Show that the nullspace of  $D - r_1$  and the nullspace of  $D - r_2$  are in the nullspace of  $P(D)$  and hence find the general solution to the differential equation.

Show that the solution to

$$P(D)f(x) = e^{\alpha x}$$

is in the nullspace of  $(D - \alpha I)P(D)$ .

Find the solution to

$$f''(x) - 5f'(x) + 6f(x) = e^x$$

with  $f(0) = 1$ ,  $f'(0) = 2$ .

Find the solution to

$$f''(x) - 5f'(x) + 6f(x) = e^{2x}$$

with the same initial conditions.