



# Mech 221 Mathematics Component

## Differential Equations

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Lectures 8-9



# Outline

## Lecture 8

First Order Autonomous Equations  
Stability of Equilibrium Points  
Another Example

## Lecture 9

The Logistic Equation  
Scaling  
Another Example

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## First Order Autonomous Equations

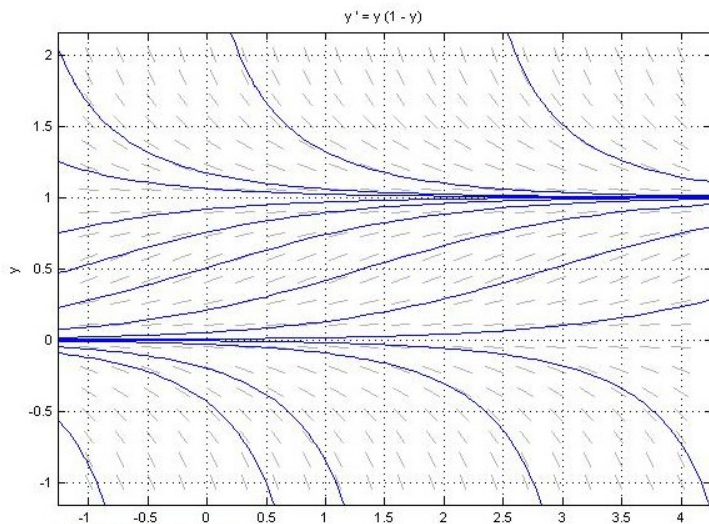
$$y' = f(y) \quad \text{with} \quad y(t_0) = y_0$$

Observe the following:

- The direction field **does not depend on  $t$**  (the definition of autonomous).
- if  $f(y) > 0$  then  $y' > 0$  and so  $y$  is increasing.
- if  $f(y) < 0$  then  $y' < 0$  and so  $y$  is decreasing.
- if  $f(y_*) = 0$  for a certain value of  $y_*$ , then  $y(t) \equiv y_*$  is a solution of the equation (an equilibrium solution).
- Autonomous equations are separable, we can solve them.

# First Order Autonomous Equations-II

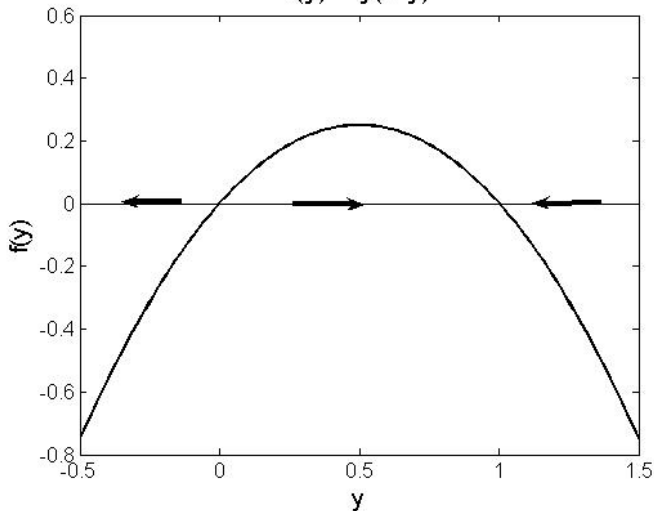
An Example:  $y' = y(1 - y)$  Direction Field



## First Order Autonomous Equations-III

An Example:  $y' = y(1 - y)$  A Different Plot

$$f(y) = y(1-y)$$





# First Order Autonomous Equations-IV

An Example:  $y' = y(1 - y)$  Sketch Solutions



# First Order Autonomous Equations-V

An Example:  $y' = y(1 - y)$  Solution



# First Order Autonomous Equations-VI

An Example:  $y' = y(1 - y)$  Solution (cont.)

# Stability of Equilibrium Points

## Stability and Instability

**Equilibrium (critical) Points** are the roots of  $f(y)$ . Each equilibrium point is a constant solution of

$$y' = f(y)$$

- An equilibrium solution  $y_*$  is called **asymptotically stable** if all solutions sufficiently close to  $y_*$  tend to  $y_*$  as  $t \rightarrow \infty$ .
- An equilibrium solution  $y_*$  is called **unstable** if all solutions sufficiently close to  $y_*$  move away from  $y_*$  as  $t \rightarrow \infty$ .

Stable but not asymptotically stable means that solutions don't move away but also don't get closer (can see periodic solutions around equilibrium points in autonomous systems of equations).

# Stability of Equilibrium Points-II

## Stability Conditions

If  $y_*$  is an equilibrium point ( $f(y_*) = 0$ ) and

- $f(y) < 0$  for  $y > y_*$  and
- $f(y) > 0$  for  $y < y_*$

then  $y_*$  is asymptotically stable. This occurs if  $f'(y_*) < 0$ .

Similarly, if  $f'(y_*) > 0$  then the equilibrium solution  $y_*$  is *unstable*.

# Stability of Equilibrium Points-III

## Example

Find and classify (as stable or unstable) the equilibrium (critical) points of

$$y' = y(1 - y)$$

# Stability of Equilibrium Points-IV

## Linearization

Let's look more carefully at what happens to solutions near equilibrium solutions. Consider

$$y(t) = y_* + u(t) \quad \text{where } |u(t)| \text{ is small}$$

in the equation

$$y' = f(y)$$



# Stability of Equilibrium Points-V

Linearization (cont).

## Another Example

A resistor is connected to a 12V battery. The resistance  $R(T)$  in Ohms decreases with temperature  $T$  in C as follows:

$$R(T) = \frac{1}{1 + T^2}$$

The resistor has a total heat capacity of 100 J/C. Find and classify equilibrium temperatures for the following 2 cases:

1. The resistor is thermally insulated
2. The resistor is not insulated, is placed in a 0C environment, and it is found that heat loss in W is given by  $1000T$ .



## Another Example-II





## Another Example-III



## Another Example-IV

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## The Logistic Equation

$$y' = ry(K - y)$$

where  $r$  and  $K$  are given, positive parameters. Questions:

1. What are the equilibrium points?
2. Are they stable or unstable?
3. What are the local decay rates for stable equilibria and local growth rates for unstable equilibria?



# The Logistic Equation-II

## Questions Answered



# The Logistic Equation-III

Questions Answered (cont.)

## Scaling

I am not going to solve

$$y' = ry(K - y)$$

because I *claim* I have **already solved it** since we solved

$$y' = y(1 - y)$$

last lecture (the logistic equation with  $r = 1$  and  $K = 1$ ). Let's see why this claim is actually true.



# Scaling-II





# Scaling-III



# Scaling-IV

## Scaling-V

Starting with

$$y' = f(y, t)$$

we can scale introduce scaled quantities

$$u = \frac{y}{Y}$$

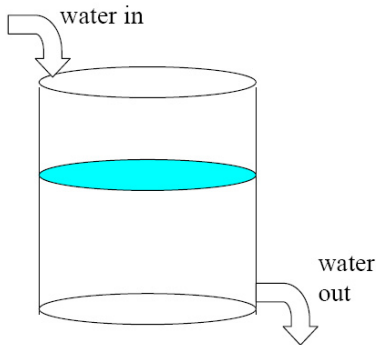
$$s = \frac{t}{T}$$

where  $Y$  and  $T$  are characteristic constant values of  $y$  and  $t$ . The resulting equation for  $u(s)$  can have desirable properties:

- $u$  and  $s$  are dimensionless
- Choosing  $Y$  and  $T$  well can lead to simplifications in the equation
- Universal equations for a class of problems can be identified.
- The relative importance of several terms in an equation can be more easily identified.
- Suitably scaled equations are easier to solve numerically.

## Another Example

Suppose a cylindrical water tank of height 1m with cross-sectional area  $1 \text{ (m}^2\text{)}$  is being filled at a rate of 1 litre/s. Water leaks out a small hole in the bottom. When the tank is completely full, the leak rate is 2 litres/s. Assume the draining rate obeys Torricelli's law (rate proportional to square root of water depth).



## Another Example-II

### Questions

1. Can the tank ever empty?
2. Can the tank ever overflow?
3. Is there a stable equilibrium water depth?
4. What is the equation for  $h(t)$ , the water depth?
5. What is the function  $h(t)$  that describes the water depth if the tank starts half full.



# Another Example-III

Answers



# Another Example-IV

Answers (cont.)

## Another Example-V

### General Equation

Derive the general equation in terms of the tank area  $A$ , maximum depth  $D$ , inflow rate  $Q_i$ , outflow rate at maximum depth  $Q_o$ . Scale the resulting equation to make it as simple as possible.



# Another Example-V

General Equation (cont.)



# Another Example-VI

General Equation (cont.)